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**A GEOMETRIC MAXIMUM PRINCIPLE FOR
VARIATIONAL PROBLEMS IN SPACES OF VECTOR
VALUED FUNCTIONS OF BOUNDED VARIATION**

ABSTRACT. We discuss variational integrals with density having linear growth on spaces of vector valued BV -functions and prove $\text{Im}(u) \subset K$ for minimizers u provided that the boundary data take their values in the closed convex set K assuming in addition that the integrand satisfies natural structure conditions.

Given a closed convex set $K \subset \mathbb{R}^N$, we say that minimizers of some variational problem have the convex hull property if they are contained in K in a sense to be made precise provided this is true for their boundary data. A prominent example is given by mass minimizing integer multiplicity m -currents T with compact support, where $m \leq N$ and where the comparison currents S are such that $\partial S = T_0$ for a $(m-1)$ -current T_0 with compact support and $\partial T_0 = 0$. Then the support of T is contained in the convex hull of $\text{spt } T_0$, which is a consequence of the monotonicity formula for stationary varifolds. We refer the reader to [14, 19.2 Theorem and 34.2 remarks]. Let us now pass to the setting of variational integrals

$$I[u, \Omega] = \int_{\Omega} f(\nabla u) dx$$

defined for functions $u: \mathbb{R}^n \supset \Omega \rightarrow \mathbb{R}^N$, Ω denoting a bounded Lipschitz domain. Suppose that we are given a function u_0 such that

$$u_0 \in W_1^1(\Omega; \mathbb{R}^N), \quad u_0(x) \in K \quad \text{a.e.}, \quad (1)$$

where $W_1^1(\Omega; \mathbb{R}^N)$ is the Sobolev space of vector-valued mappings (see, e.g., [1]). Let us further assume that $f(Z) = h(|Z|)$ with

$$h: [0, \infty) \rightarrow [0, \infty) \quad \text{strictly increasing and convex.} \quad (2)$$

Key words and phrases: Functions of bounded variation, linear growth problems, minimizers, convex hull property, maximum principle.

Then, if $u \in W_1^1(\Omega; \mathbb{R}^N)$ minimizes $I[\cdot, \Omega]$ w.r.t. the boundary data u_0 , i.e.,

$$\begin{cases} I[u, \Omega] < \infty, & u - u_0 \in W_1^1(\Omega; \mathbb{R}^N) \quad \text{and} \\ I[u, \Omega] \leq I[v, \Omega] & \text{for all } v \in u_0 + \overset{\circ}{W}_1^1(\Omega; \mathbb{R}^N), \end{cases}$$

it follows that $u(x) \in K$ for almost any $x \in \Omega$. A simple proof is given by the following observation: let $\Phi: \mathbb{R}^N \rightarrow K$ denote the nearest-point-projection being Lipschitz with $\text{Lip}(\Phi) = 1$. From [4], comments given at the beginning of the proof of Theorem 3.96, we see that $v = \Phi(u)$ is admissible and satisfies $|\nabla v| \leq \text{Lip}(\Phi)|\nabla u| = |\nabla u|$. Using the properties of h stated in (2) combined with $|\nabla v| \leq |\nabla u|$, we get from the minimality of u that $I[u, \Omega] = I[v, \Omega]$, and as it is outlined below, this will lead to $\nabla u = \nabla v$; hence $u = v$ and in conclusion $u \in K$, a.e. We remark first that a related maximum principle is due to D'Ottavio, Leonetti and Musciano [9], and second that a similar argument together with a proof of the chain rule in the Lipschitz setting has been presented in [6]. However, the reader should note at this stage that a much more general chain rule formula implying $|\nabla(\Phi \circ u)| \leq \text{Lip}(\Phi)|\nabla u|$ is due to Ambrosio and Dal Maso [2]. As a matter of fact the existence of a minimizer u in a suitable Sobolev class requires that h is of superlinear growth, and therefore in general can not be guaranteed if in addition to (2) the function h satisfies

$$\bar{c} := \lim_{t \rightarrow \infty} \frac{h(t)}{t} \quad \text{exists in } (0, \infty), \quad (3)$$

which means that now h is just of linear growth.

W.l.o.g. we will also assume that $h(0) = 0$. Based on ideas of De Giorgi (see the recent book [10] for an overview on his work), of Giusti [11], of Giaquinta, Modica, Souček [12], of Goffman and Serrin [13], of Ambrosio and Dal Maso [3] and of Buttazzo [8] it is possible to introduce suitable concepts of generalized solutions to the problem

$$I[u, \Omega] = \int_{\Omega} h(|\nabla u|) dx \rightarrow \min \quad \text{in } u_0 + \overset{\circ}{W}_1^1(\Omega; \mathbb{R}^N). \quad (\mathcal{P})$$

Let

$$\mathcal{M} := \{u \in BV(\Omega; \mathbb{R}^N) : u \text{ is a } L^1\text{-cluster point of a minimizing sequence of problem } \mathcal{P}\}$$

and define $K[\cdot, \Omega] : BV(\Omega; \mathbb{R}^N) \rightarrow \mathbb{R}$,

$$K[u, \Omega] := \int_{\Omega} h(|\nabla^a u|) dx + \bar{c} |\nabla^s u|(\Omega) + \int_{\partial\Omega} \bar{c} |(u_0 - u) \otimes \mathcal{N}| d\mathcal{H}^{n-1},$$

where $BV(\Omega; \mathbb{R}^N)$ is the space of functions of bounded variation (see [4] or [11]), \mathcal{N} is the exterior normal of $\partial\Omega$ and where we have used the decomposition of the vector measure ∇u in its absolutely continuous part $\nabla^a u \ll \mathcal{L}^n$ and its singular part $\nabla^s u$. According to a theorem of Besicovitch ([4, Theorem 2.22]) we have $\nabla^a u \in L^1(\Omega; \mathbb{R}^{nN})$ and

$$\nabla^a u(x) = \lim_{\rho \downarrow 0} \frac{\nabla u(B_\rho(x))}{\mathcal{L}^n(B_\rho(x))} \quad (4)$$

holds for \mathcal{L}^n -a.a. $x \in \Omega$. Note that on account of (3) the recession function

$$f_\infty(Z) := \lim_{t \rightarrow 0} \frac{f(tZ)}{t}, \quad Z \in \mathbb{R}^{nN},$$

equals $\bar{c}|Z|$. Hence, we have the more familiar formula

$$\begin{aligned} K[u, \Omega] &= \int_{\Omega} f(\nabla^a u) dx + \int_{\Omega} f_\infty\left(\frac{\nabla^s u}{|\nabla^s u|}\right) d|\nabla^s u| \\ &\quad + \int_{\partial\Omega} f_\infty((u_0 - u) \otimes \mathcal{N}) d\mathcal{H}^{n-1} \end{aligned}$$

for the extension of I to the space $BV(\Omega; \mathbb{R}^N)$. We recall the following facts established in [7] (compare also [5, Appendix A1]):

- (i) $I[\cdot, \Omega] = K[\cdot, \Omega]$ on $u_0 + \mathring{W}_1^1(\Omega; \mathbb{R}^N)$;
- (ii) $K[\cdot, \Omega] \rightarrow \min$ admits at least one solution in $BV(\Omega; \mathbb{R}^N)$;
- (iii) these minimizers are exactly the elements of \mathcal{M} ;
- (iv) $\inf_{u_0 + \mathring{W}_1^1(\Omega; \mathbb{R}^N)} I[\cdot, \Omega] = \inf_{BV(\Omega; \mathbb{R}^N)} K[\cdot, \Omega]$.

Based on these facts it is reasonable to address the elements of the set \mathcal{M} as generalized solutions of problem (\mathcal{P}) .

Now we can state our main result:

Theorem 1. *Suppose that u_0 satisfies (1) for a closed and convex set $K \subset \mathbb{R}^N$. Assume further that we have (2) and (3) for the density h . Then it holds $u(x) \in K$, a.e., for any generalized solution of problem (P).*

Corollary 1 (Maximum-principle). *Suppose that h satisfies (2) and (3). Assume further that $u_0 \in W_1^1(\Omega; \mathbb{R}^N) \cap L^\infty(\Omega; \mathbb{R}^N)$. Then any generalized minimizer $u \in BV(\Omega; \mathbb{R}^N)$ of problem (P) satisfies $\|u\|_{L^\infty(\Omega)} \leq \|u_0\|_{L^\infty(\Omega)}$.*

Remark 1. The proof of Theorem 1 given below immediately extends to integrands of the form

$$f(Z) = \sum_{i=1}^n h_i(|Z_i|), \quad Z = (Z_1, \dots, Z_n) \in \mathbb{R}^{nN}, \quad Z_i \in \mathbb{R}^N,$$

with functions h_1, \dots, h_n satisfying (2) and having the property that

$$\bar{c}_i := \lim_{t \rightarrow \infty} \frac{h_i(t)}{t}$$

exists in $(0, \infty)$. In this case, it holds

$$f_\infty(Z) = \sum_{i=1}^n \bar{c}_i |Z_i|.$$

Of course any other additive decomposition of f depending on the moduli of the Z_i can be considered, e.g.,

$$f(Z) = h_1(\sqrt{|Z_1|^2 + |Z_2|^2}) + h_2(|Z_3|)$$

or

$$f(Z) = h_1(|Z_1|) + h_2(\sqrt{|Z_2|^2 + |Z_3|^2})$$

are admissible in the case $n = 3$. In fact, a careful inspection of the proof of the chain rule shows the validity of

$$|\partial_i(\Phi \circ u)| \leq \text{Lip}(\Phi) |\partial_i u|, \quad i = 1, \dots, n,$$

so that $|\partial_i(\Phi \circ u)| \leq |\partial_i u|$.

Proof. We fix a Lipschitz domain $\widehat{\Omega} \ni \Omega$, extend u_0 to an element of $W_1^1(\widehat{\Omega}; \mathbb{R}^N)$ with values in K and let

$$BV_{u_0}(\Omega; \mathbb{R}^N) := \{w \in BV(\widehat{\Omega}; \mathbb{R}^N) : w = u_0 \text{ on } \widehat{\Omega} - \Omega\}.$$

Following [12] we define

$$\begin{aligned} \widehat{I}[w, \widehat{\Omega}] &:= \int_{\widehat{\Omega}} f(\nabla^a w) dx + \int_{\widehat{\Omega}} f_\infty\left(\frac{\nabla^s w}{|\nabla^s w|}\right) d|\nabla^s w| \\ &= \int_{\widehat{\Omega}} h(|\nabla^a w|) dx + \bar{c}|\nabla^s w|(\widehat{\Omega}) \end{aligned}$$

for $w \in BV_{u_0}(\Omega; \mathbb{R}^N)$, and as outlined in [7] we have

$$\widehat{I}[w, \widehat{\Omega}] = K[w|_\Omega, \Omega] + \text{const}.$$

Conversely, if $v \in BV(\Omega; \mathbb{R}^N)$ and if we put

$$\widehat{v} := \left\{ \begin{array}{ll} v & \text{on } \Omega \\ u_0 & \text{on } \widehat{\Omega} - \Omega \end{array} \right\} \in BV_{u_0}(\Omega; \mathbb{R}^N),$$

then

$$\widehat{I}[\widehat{v}, \widehat{\Omega}] = K[v, \Omega] + \text{const},$$

where $\text{const} = \int_{\widehat{\Omega} - \Omega} h(|\nabla u_0|) dx$. Due to this observation it is sufficient to consider a solution $u \in BV_{u_0}(\Omega; \mathbb{R}^N)$ of

$$\widehat{I}[\cdot, \widehat{\Omega}] \rightarrow \min \quad \text{in } BV_{u_0}(\Omega; \mathbb{R}^N)$$

and to prove that $u(x) \in K$ almost everywhere.

For this purpose, we consider the retraction $\Phi: \mathbb{R}^N \rightarrow K$ and let as before $v := \Phi \circ u$. According to the comments given at the beginning of the proof of Theorem 3.96 in [4] v is in $BV(\widehat{\Omega}; \mathbb{R}^N)$ and (recall $\text{Lip}(\Phi) = 1$)

$$|\nabla v| \leq \text{Lip}(\Phi)|\nabla u| = |\nabla u|, \quad (5)$$

where $|\nabla v|$ and $|\nabla u|$ denote the total variations of the vector measures ∇v and ∇u . Here we like to emphasize again that a general chain rule

formula as stated for example in Theorem 3.101 of [4] is due to Ambrosio and Dal Maso [2], and that (5) is a simple consequence of this important formula. Clearly $v \in BV_{u_0}(\Omega; \mathbb{R}^N)$ so that

$$\widehat{I}[u, \widehat{\Omega}] \leq \widehat{I}[v, \widehat{\Omega}]. \quad (6)$$

Now we use (4) for u and v which implies in combination with (5) for \mathcal{L}^n -a.a. $x \in \widehat{\Omega}$

$$|\nabla^a v(x)| = \lim_{\rho \downarrow 0} \frac{|\nabla v|(B_\rho(x))}{\mathcal{L}^n(B_\rho(x))} \leq \lim_{\rho \downarrow 0} \frac{|\nabla u|(B_\rho(x))}{\mathcal{L}^n(B_\rho(x))} = |\nabla^a u(x)|,$$

and the monotonicity of h gives

$$\int_{\widehat{\Omega}} h(|\nabla^a v|) dx \leq \int_{\widehat{\Omega}} h(|\nabla^a u|) dx. \quad (7)$$

Quoting [4, Proposition 3.92(a)], for a function $w \in BV(\widehat{\Omega}; \mathbb{R}^N)$ we may write

$$\nabla^s w = \nabla w \llcorner S_w, \quad S_w := \left\{ x \in \widehat{\Omega} : \lim_{\rho \downarrow 0} \frac{|\nabla w|(B_\rho(x))}{\mathcal{L}^n(B_\rho(x))} = \infty \right\}, \quad (8)$$

and deduce from (5) that

$$S_v \subset S_u, \quad (9)$$

since

$$|\nabla v|(B_\rho(x)) \leq |\nabla u|(B_\rho(x)).$$

Next, we use (5), (8), and (9) and obtain

$$|\nabla^s v|(\widehat{\Omega}) = |\nabla v|(S_v) \leq |\nabla u|(S_u) = |\nabla^s u|(\widehat{\Omega}), \quad (10)$$

which in combination with (7) leads to

$$\widehat{I}[v, \widehat{\Omega}] \leq \widehat{I}[u, \widehat{\Omega}].$$

By (6), we must have

$$\widehat{I}[v, \widehat{\Omega}] = \widehat{I}[u, \widehat{\Omega}],$$

and, by (7) and (10), this is only possible if

$$\int_{\widehat{\Omega}} h(|\nabla^a u|) dx = \int_{\widehat{\Omega}} h(|\nabla^a v|) dx, \quad (11)$$

$$|\nabla^s u|(\widehat{\Omega}) = |\nabla^s v|(\widehat{\Omega}). \quad (12)$$

From (11) and $|\nabla^a v| \leq |\nabla^a u|$ and requirement (2) it is immediate that

$$|\nabla^a u| = |\nabla^a v| \quad \mathcal{L}^n\text{-a.e. on } \widehat{\Omega}. \quad (13)$$

If $E \subset \widehat{\Omega}$ is a Borel set, then analogous to (10) we obtain from (5) and (9)

$$|\nabla^s v|(E) = |\nabla v|(S_v \cap E) \leq |\nabla u|(S_u \cap E) = |\nabla^s u|(E). \quad (14)$$

At the same time, using (14) with E replaced by $\widehat{\Omega} - E$ and (12), we find that

$$\begin{aligned} |\nabla^s v|(E) &= |\nabla^s v|(\widehat{\Omega}) - |\nabla^s v|(\widehat{\Omega} - E) \geq |\nabla^s v|(\widehat{\Omega}) - |\nabla^s u|(\widehat{\Omega} - E) \\ &= |\nabla^s u|(\widehat{\Omega}) - |\nabla^s u|(\widehat{\Omega} - E) = |\nabla^s u|(E). \end{aligned}$$

In view of (14), it is shown that

$$|\nabla^s u| = |\nabla^s v|. \quad (15)$$

Suppose that

$$\mathcal{L}^n(\{x \in \widehat{\Omega} : \nabla^a u(x) \neq \nabla^a v(x)\}) > 0. \quad (16)$$

We have

$$\int_{[\nabla^a u \neq \nabla^a v]} (|\nabla^a u| + |\nabla^a v| - |\nabla^a u + \nabla^a v|) dx > 0, \quad (17)$$

since otherwise

$$|\nabla^a u + \nabla^a v| = |\nabla^a u| + |\nabla^a v|$$

a.e. on $[\nabla^a u \neq \nabla^a v]$ and, therefore,

$$\nabla^a u = \lambda \nabla^a v$$

on this set with a nonnegative function λ . However, (13) then leads to the contradiction $\lambda = 1$. From (17) we get recalling (2)

$$\begin{aligned} \int_{\widehat{\Omega}} h\left(\left|\nabla^a\left(\frac{u+v}{2}\right)\right|\right) dx &< \int_{\widehat{\Omega}} h\left(\frac{1}{2}|\nabla^a u| + \frac{1}{2}|\nabla^a v|\right) dx \\ &\leq \frac{1}{2} \int_{\widehat{\Omega}} h(|\nabla^a u|) dx + \frac{1}{2} \int_{\widehat{\Omega}} h(|\nabla^a v|) dx, \end{aligned}$$

and since $|\nabla^s(u+v)| \leq |\nabla^s u| + |\nabla^s v|$ it follows from (13) and (15) that

$$\widehat{I}\left[\frac{u+v}{2}, \widehat{\Omega}\right] < \widehat{I}[u, \widehat{\Omega}]. \quad (18)$$

But $(u+v)/2$ belongs to $BV_{u_0}(\Omega; \mathbb{R}^N)$, thus the strict inequality (18) contradicts the minimizing property of u , and assumption (16) is wrong which means

$$\nabla^a u = \nabla^a v \quad \mathcal{L}^n\text{-a.e. on } \widehat{\Omega}. \quad (19)$$

Consider the measure $\mu := |\nabla^s u|$. Using (15) we find μ -measurable functions $\Theta_u, \Theta_v: \widehat{\Omega} \rightarrow \mathbb{R}^{nN}$ s.t. $|\Theta_u| = 1 = |\Theta_v|$ μ -a.e. and

$$\nabla^s u = \Theta_u \lrcorner \mu, \quad \nabla^s v = \Theta_v \lrcorner \mu. \quad (20)$$

Let us assume that

$$\left|\nabla^s\left(\frac{u+v}{2}\right)\right|(\widehat{\Omega}) < |\nabla^s u|(\widehat{\Omega}). \quad (21)$$

This implies on account of (19)

$$\widehat{I}\left[\frac{u+v}{2}, \widehat{\Omega}\right] = \int_{\widehat{\Omega}} h(|\nabla^a u|) dx + \bar{c} \left|\nabla^s\left(\frac{u+v}{2}\right)\right|(\widehat{\Omega}) < \widehat{I}[u, \widehat{\Omega}],$$

which is in contradiction to the minimality of u . Therefore we have in place of (21)

$$\left|\int_{\widehat{\Omega}} \frac{1}{2}(\Theta_u + \Theta_v) d\mu\right| = \mu(\widehat{\Omega}).$$

Hence,

$$\mu(\widehat{\Omega}) \leq \frac{1}{2} \int_{\widehat{\Omega}} |\Theta_u + \Theta_v| d\mu \leq \frac{1}{2} \int_{\widehat{\Omega}} (|\Theta_u| + |\Theta_v|) d\mu = \mu(\widehat{\Omega})$$

and in conclusion

$$|\Theta_u + \Theta_v| = |\Theta_u| + |\Theta_v| \quad \mu\text{-a.e.}$$

For this reason, we can write

$$\Theta_u = \bar{\lambda} \Theta_v$$

with $\bar{\lambda}$ nonnegative and μ -measurable, but $|\Theta_u| = 1 = |\Theta_v|$ gives $\bar{\lambda} \equiv 1$, i.e., $\Theta_u = \Theta_v$ μ -a.e. From (20) it follows $\nabla^s u = \nabla^s v$, which, together with (19) shows that $\nabla u = \nabla v$. Quoting Proposition 3.2 of [4], we see $u - v \equiv \text{const}$ and $u = u_0 = v$ on $\widehat{\Omega} - \Omega$ yields $u = v$ and in conclusion $u(x) \in K$, a.e. The proof of Theorem 1 is complete. \square

For the sake of completeness, we have a look at the scalar case for which it is possible to give up the special structure of the integrand and to obtain a maximum principle close to the classical one. To be precise, let us assume that $F: \mathbb{R}^n \rightarrow [0, \infty)$ is strictly convex together with $F(0) = 0$. For $u_0 \in W_1^1(\Omega)$ we consider again the variational problem \mathcal{P}

$$I[u, \Omega] = \int_{\Omega} F(\nabla u) dx \rightarrow \min \quad \text{in } u_0 + \overset{\circ}{W}_1^1(\Omega), \quad (\mathcal{P})$$

and observe

$$\inf_{\partial\Omega} u_0 \leq u \leq \sup_{\partial\Omega} u_0 \quad (22)$$

provided that we can find a solution $u \in W_1^1(\Omega)$ of (\mathcal{P}) . In fact, if we assume $M := \sup_{\partial\Omega} u_0 < \infty$, then from

$$I[u, \Omega] \leq I[\min(u, M), \Omega]$$

we deduce that

$$\int_{[u > M]} F(\nabla u) dx = 0,$$

and $0 \leq F(\nabla u/2) < F(\nabla u)/2$ on $[\nabla u \neq 0]$ implies $\nabla u = 0$ on $[u > M]$. Hence, $\nabla \max(u, M) = 0$, which shows $u \leq M$.

Let us now assume that F is of linear growth, i.e., with constants a , $A > 0$, b , and $B \in \mathbb{R}$ it holds

$$a|\xi| + b \leq F(\xi) \leq A|\xi| + B \quad (23)$$

for all $\xi \in \mathbb{R}^n$. Moreover, we require

$$F(-\eta) = F(\eta) \quad \text{for all } \eta \in \mathbb{R}^n. \quad (24)$$

Then we have

Theorem 2. *Let the strictly convex function F satisfy (23) and (24) together with $F(0) = 0$. If $u \in \mathcal{M}$ denotes a generalized minimizer of problem (P), then (the slightly weaker variant of (22))*

$$\inf_{\Omega} u_0 \leq u(x) \leq \sup_{\Omega} u_0 \quad (25)$$

is satisfied for a.a. $x \in \Omega$.

Proof. It is sufficient to consider the case $M := \sup_{\Omega} u_0 < \infty$ and to prove the second inequality stated in (25). We extend u_0 to a function of class $W_1^1(\widehat{\Omega})$ on a bounded Lipschitz domain $\widehat{\Omega} \ni \Omega$ assuming that this extension – again denoted by u_0 – still satisfies $u_0 \leq M$, a.e. (now on $\widehat{\Omega}$), since otherwise we may compose it with the function $\psi(t) := \min(M, t)$, $t \in \mathbb{R}$. As outlined in the proof of Theorem 1 the claim of Theorem 2 will follow if we can show that any solution $u \in BV_{u_0}(\Omega)$ of

$$\widehat{I}[w, \widehat{\Omega}] := \int_{\widehat{\Omega}} F(\nabla^a w) dx + \int_{\widehat{\Omega}} F_{\infty} \left(\frac{\nabla^s w}{|\nabla^s w|} \right) d|\nabla^s w| \rightarrow \min \quad \text{in } BV_{u_0}(\Omega)$$

satisfies $u \leq M$ a.e. Quoting the chain rule for real valued functions as stated in Theorem 3.99 of [4], we have $v := \psi \circ u \in BV_{u_0}(\Omega)$ together with

$$\nabla v = \psi'(u) \nabla^a u \llcorner \mathcal{L}^n + (\psi(u^+) - \psi(u^-)) \nu_u \mathcal{H}^{n-1} \llcorner J_u + \psi'(\tilde{u}) \nabla^c u,$$

where our notation follows the terminology of [4]. Let us look at the part $\psi'(u) \nabla^a u \llcorner \mathcal{L}^n$ of the vector measure ∇v being absolutely continuous w.r.t. \mathcal{L}^n . It holds $\psi'(u) = 0$ a.e. on the set $[u > M]$, whereas $\psi'(u) = 1$, a.e.,

on $[u < M]$. Since the density $\nabla^a u$ equals the approximative differential of u (see [4, Theorem 3.83]), and since the approximative differential of u vanishes, a.e., on $[u = M]$ (see [4, Proposition 3.73(c)]), we get

$$\int_{\widehat{\Omega}} F(\nabla^a v) dx = \int_{[u < M]} F(\nabla^a u) dx. \quad (26)$$

Notice that the measures $\nabla^j v$ and $\nabla^c v$ are mutually orthogonal; hence, we can write

$$\begin{aligned} \int_{\widehat{\Omega}} F_{\infty} \left(\frac{\nabla^s v}{|\nabla^s v|} \right) d|\nabla^s v| &= \int_{J_u} F_{\infty}(\psi(u^+) - \psi(u^-)) \nu_u d\mathcal{H}^{n-1} \\ &+ \int_{\widehat{\Omega}} F_{\infty} \left(\psi'(\tilde{u}) \frac{\nabla^c u}{|\nabla^c u|} \right) d|\nabla^c u|. \end{aligned} \quad (27)$$

The function $\psi'(\tilde{u})$ has values in $\{0, 1\}$, which means that

$$F_{\infty} \left(\psi'(\tilde{u}) \frac{\nabla^c u}{|\nabla^c u|} \right) \leq F_{\infty} \left(\frac{\nabla^c u}{|\nabla^c u|} \right) \quad |\nabla^c u| \text{-a.e.}$$

At the same time, we have \mathcal{H}^{n-1} -a.e. on J_u

$$\begin{aligned} &F_{\infty}((\psi(u^+) - \psi(u^-)) \nu_u) \\ &= |\psi(u^+) - \psi(u^-)| F_{\infty}(\text{sign}[\psi(u^+) - \psi(u^-)] \nu_u) \\ &= |\psi(u^+) - \psi(u^-)| F_{\infty}(\nu_u) \\ &\leq |u^+ - u^-| F_{\infty}(\nu_u) \\ &= F_{\infty}((u^+ - u^-) \nu_u). \end{aligned}$$

Here, the first equality sign follows from the fact that the recession function is positively homogeneous of degree one, the second is a consequence of (24) and the last equation is established in the same way. Combing the inequalities from above with (26) and (27) and using the minimality of u we obtain

$$\int_{[u \geq M]} F(\nabla^a u) dx = 0, \quad (28)$$

together with

$$\int_{J_u} F_\infty((\psi(u^+) - \psi(u^-))\nu_u) d\mathcal{H}^{n-1} = \int_{J_u} F_\infty((u^+ - u^-)\nu_u) d\mathcal{H}^{n-1} \quad (29)$$

and

$$\int_{\hat{\Omega}} F_\infty\left(\psi'(\tilde{u}) \frac{\nabla^c u}{|\nabla^c u|}\right) d|\nabla^c u| = \int_{\hat{\Omega}} F_\infty\left(\frac{\nabla^c u}{|\nabla^c u|}\right) d|\nabla^c u|. \quad (30)$$

From (28), we deduce using the strict convexity of F , together with $F(0) = 0$, that

$$\nabla^a u = 0 \quad \mathcal{L}^n\text{-a.e. on } [u \geq M]. \quad (31)$$

From (29) and

$$F_\infty((\psi(u^+) - \psi(u^-))\nu_u) \leq F_\infty((u^+ - u^-)\nu_u),$$

\mathcal{H}^{n-1} -a.e. on J_u it follows that

$$F_\infty((\psi(u^+) - \psi(u^-))\nu_u) = F_\infty((u^+ - u^-)\nu_u) \quad (32)$$

\mathcal{H}^{n-1} -a.e. on J_u , since otherwise we would have a contradiction to the minimality of u . (32) gives

$$|\psi(u^+) - \psi(u^-)| = |u^+ - u^-| \quad (33)$$

\mathcal{H}^{n-1} -a.e. on J_u (recall $F_\infty(t\xi) = |t|F_\infty(\xi)$) but by definition of ψ this means

$$\psi(u^+) - \psi(u^-) = u^+ - u^- \quad (34)$$

\mathcal{H}^{n-1} -a.e. on J_u . In the same way, we obtain from (30), from

$$F_\infty\left(\psi'(\tilde{u}) \frac{\nabla^c u}{|\nabla^c u|}\right) \leq F_\infty\left(\frac{\nabla^c u}{|\nabla^c u|}\right)$$

and from the minimality of u that

$$\psi'(\tilde{u}) = 1 \quad |\nabla^c u| - \text{a.e.} \quad (35)$$

Recalling the formula for ∇v and using (31), (34), and (35) we arrive at $\nabla v = \nabla u$; hence, $v = u$ and in conclusion $u \leq M$ a.e. on $\hat{\Omega}$. \square

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Поступило 30 мая 2010 г.