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On elastic waves in topographic waveguides*

A.A. Matskovskiy, G.L. Zavorokhin

*St.Petersburg Department of V.A.Steklov Institute of Mathematics of the Russian
Academy of Sciences, 27, Fontanka, 191023 St.Petersburg, Russia*

Аннотация

The existence of elastic waves with displacements localized along the edge of a triangular protrusion on the surface of an elastic half-space was rigorously proven by V. M. Babich in [1] for isotropic homogeneous topographic waveguides with an interior angle less than $\frac{\pi}{2}$. We extend Babich's result by proving the existence of such localized waves for interior angles exceeding $\frac{\pi}{2}$. Furthermore, our ansatz allows us to separately analyze the existence of symmetric and antisymmetric modes.

Keywords: topographic waveguide, wedge waves, Rayleigh wave, variational method, discrete spectrum.

Dedicated to the memory of our teacher, Professor V.M. Babich

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1 Introduction

The propagation of elastic waves along topographic features such as ridges and wedges (see Fig. 1) on an otherwise flat surface has been a subject of long-standing interest in seismology, nondestructive testing, and surface acoustic wave devices. These structures support guided modes — known as wedge waves or topographic modes — that are localized near the ridge tip and propagate with phase velocity strictly less than that of the Rayleigh wave c_R .

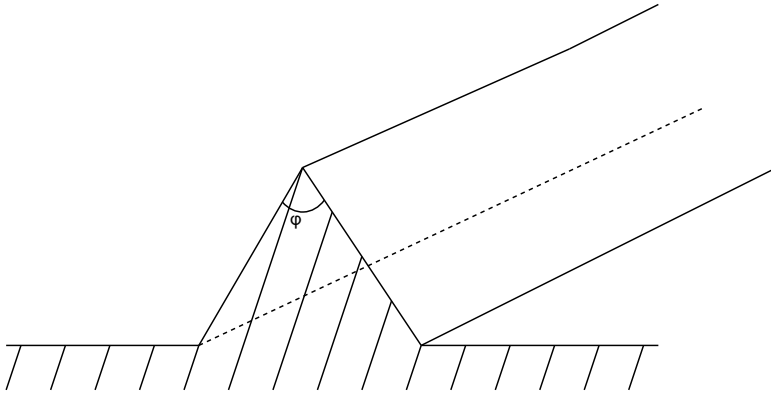


Fig. 1. Topographic waveguide.

Рис. 1: Topographic waveguide.

Numerical evidence of such modes dates back to the 1970s [3–6]. Physically rigorous asymptotic and ray methods were developed in the 1980s–1990s (see the review [8, Ch. 10]). Mathematically rigorous existence proofs appeared later: Bonnet–Duterte–Joly [9] proved existence for sufficiently small apex angles, while V. M. Babich [1] extended the result to all acute apex angles $\varphi < \pi/2$ using a variational approach in the short-wavelength limit ($k \rightarrow +\infty$).

The boundary case of a right apex angle $\varphi = \pi/2$ remained open because Babich’s original trial function (a Rayleigh wave with an “escaping” cut-off function of width $O(1)$) yields a Rayleigh quotient asymptotics $c_R^2 k^2 + O(1)$, insufficient to guarantee a discrete eigenvalue below $c_R^2 k^2$. However, this gap was recently closed by A.A. Matskovskiy and G.L. Zavorokhin [12], who proved the existence of a localized waveguide mode for the right-angle case using a modified variational construction.

Building upon the method developed in [11] for an infinite elastic wedge, we propose a more sophisticated ansatz for the test functions, in contrast to that of [1]. As a result, we prove the existence of localized wedge waves within a certain range of angles greater than $\pi/2$. Furthermore, our ansatz enables the distinction between the existence of symmetric and antisymmetric modes. For some (negative) values of Poisson’s ratio $\sigma = \frac{\lambda}{2(\lambda+\mu)}$, the existence of both types of waves is established.

2 Problem Statement. A result due to V.M. Babich

We assume that Ξ is a domain in $\mathbb{R}^3 = \{(x_1, x_2, x_3) : x_i \in \mathbb{R}, i = 1, 2, 3\}$, described by the inequality $x_2 < f(x_1)$, where $f(x_1)$ is a nonnegative continuous function defined for $x_1 \in \mathbb{R}$ and vanishing outside a finite interval $[a, b]$. Moreover, the graph of $f(x_1)$ for $a \leq x_1 \leq b$ is assumed to consist of two rectilinear segments $[aM]$ and $[Mb]$ ($f(a) = f(b) = 0$, $M = (x_0, f(x_0))$, $x_0 \in (a, b)$, $f(x_0) > 0$) forming an angle φ at M . The domain Ξ is a topological product: $\Xi = \Omega \times \mathbb{R}$, where Ω is the domain $x_2 < f(x_1)$ on the (x_1, x_2) -plane.

Let $\mathbf{U}(t, x_1, x_2, x_3) = (U_1, U_2, U_3)$ be a solution of the elastodynamic equations in Ξ ,

$$\rho \mathbf{U}_{tt} = (\lambda + \mu) \nabla (\nabla \cdot \mathbf{U}) + \mu \Delta \mathbf{U} = 0,$$

$$\rho, \lambda, \mu = \text{const}, \quad \rho > 0, \quad \mu > 0, \quad \lambda + \frac{2}{3}\mu > 0,$$

that has the form

$$\mathbf{U} = e^{-i\omega t + ikx_3} \mathbf{u}(x_1, x_2), \quad \omega, k = \text{const}, \quad \omega > 0, \quad k > 0,$$

and satisfies the traction-free boundary condition on $\partial\Xi$. We get the following equation for \mathbf{u} in Ω :

$$\rho \omega^2 \mathbf{u} = \mathcal{L}(ik) \mathbf{u}, \tag{1}$$

where

$$\mathcal{L}(ik) \mathbf{u} = -(\lambda + \mu) \nabla (\nabla \cdot \mathbf{u}) - \mu \Delta \mathbf{u}.$$

On the right-hand side of the last identity, the differentiation $\frac{\partial}{\partial x_3}$ is assumed to be replaced by multiplication by ik .

We subject the vector (2.2) to the traction-free boundary condition on $\partial\Omega$ (i.e., for $x_2 = f(x_1)$). We arrive at the identity

$$\mathcal{N}(ik) \mathbf{u} = 0, \tag{2}$$

where $\mathcal{N}(ik)$ is a first order differential operator depending on k .

Later, we shall describe the meaning of the equation and boundary conditions more precisely. We use the notation employed in [1]. Without loss of generality, we put the density $\rho = 1$.

If a function $\mathbf{u} \not\equiv 0$ satisfies equation (2.3) and the boundary conditions (2.4), and belongs to $(L^2(\Omega))^3$ (i.e., \mathbf{u} is a vector-valued eigenfunction of the operator $\mathcal{L}(ik)$ that corresponds to the boundary conditions (2.4)), then the vector-valued function (2.2) is called a *localized waveguide mode*. This paper provides a rigorous proof of the existence of localized waveguide modes.

The variational (weak) formulation of the problem (1)–(2) refers to the integral identity

$$a_\Omega(ik; u, v) := \int_{\Omega} \sigma_{nm}[u] \overline{\partial_m v_n} dx_1 dx_2 = \omega^2(u, v)_\Omega, \quad v \in (H^1(\Omega))^3, \tag{3}$$

where bar stands for complex conjugation and $(\cdot, \cdot)_\Omega$ for the natural inner product in $(L^2(\Omega))^3$. The quadratic form $a_\Omega(ik; u, u)$ in $(L^2(\Omega))^3$ with domain $(H^1(\Omega))^3$ is symmetric, positive and closed. Therefore, the boundary value problem (1)–(2) is associated with

an unbounded positive definite self-adjoint operator $\mathcal{A}(ik)$ in the space $(L^2(\Omega))^3$ (see, e.g., [13, Ch. 10]).

It is shown in [9] that the essential spectrum of this operator coincides with the ray $[\mathbf{c}_R^2 k^2, +\infty)$. Consequently, only discrete spectrum may occur below the cutoff point $\omega_R^2 = \mathbf{c}_R^2 k^2$. If this spectrum is non-empty, the corresponding eigenvector generates a localized wedge mode propagating along the edge with a velocity less than \mathbf{c}_R . Since the problem possesses a plane of symmetry, the operator $\mathcal{A}(ik)$ can be decomposed by splitting the space $(H^1(\Omega))^3$ into subspaces of antisymmetric (\mathcal{H}_a) and symmetric (\mathcal{H}_s) displacements. This decomposition creates the fundamental possibility for the existence of both antisymmetric (flexural) and symmetric modes.

According to the variational principle, the lower bound of the spectrum of the operator $\mathcal{A}(ik)$ is equal to $\inf_{(H^1(\Omega))^3} \Phi(u)$, where

$$\Phi(u) := \frac{a_\Omega(ik; u, u)}{(u, u)_\Omega} \quad (4)$$

is the Rayleigh quotient.

To prove the existence of the discrete spectrum, it suffices to present a function $u^{test} \in (H^1(\Omega))^3$ such that

$$\Phi(u^{test}) < c_R^2 k^2. \quad (5)$$

In [1], to construct this test function, the coordinate system was placed as shown in Fig. 3. On the interval $[0, d]$, the part of the boundary $\partial\Omega$ not lying on the x_1 -axis is the rectilinear segment described by the equation $x_2 = x_1 \tan(\varphi)$, $0 < \varphi < \frac{\pi}{2}$.

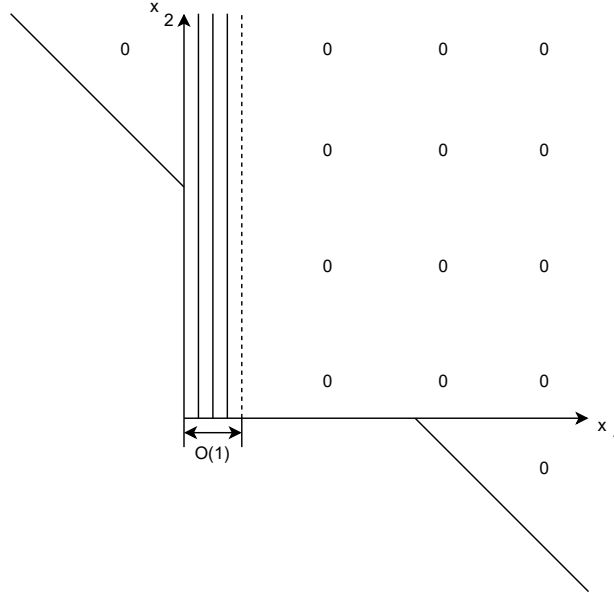


Fig. 2. Waveguide cross-section.

Рис. 2: Waveguide cross-section.

As a test function it was taken

$$u_k^{test}(x_1, x_2) = \begin{cases} \eta(x_1)u^R(x_2), & \text{in } \Omega_1, \\ 0, & \text{in } \Omega \setminus \Omega_1, \end{cases} \quad (6)$$

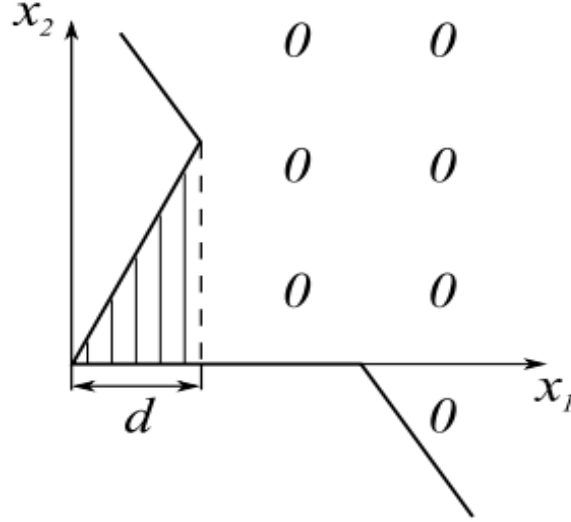


Рис. 3: Waveguide cross-section. Domain Ω_1 .

where Ω_1 is the triangle

$$0 \leq x_1 \leq d, \quad 0 \leq x_2 \leq x_1 \tan \varphi$$

(see Fig. 3),

$$\eta(x_1) = \begin{cases} 1, & \text{if } 0 \leq x_1 < d', \\ 0, & \text{if } x_1 > d, \end{cases} \quad (7)$$

is the cut-off function defined for $x_1 \geq 0$,

$$0 < d' < d, \quad d, d' = \text{const}, \quad \eta \geq 0, \quad \frac{d\eta}{dx} \leq 0, \quad \eta \in C^\infty(\mathbb{R}_+),$$

and

$$U^R(x_1, x_2, x_3, t) = e^{-i\omega t + ikx_3} u^R(x_2), \quad (8)$$

is the Rayleigh wave [2] traveling in the direction $(0,0,1)$ and leaving the plane $x_2 = 0$ free of stresses.

It turns out that

$$\Phi(u_k^{test}) = c_R^2 k^2 - ck + O(1), \quad k \rightarrow +\infty, \quad (9)$$

where $c > 0$ for $\varphi < \frac{\pi}{2}$. Then (9) implies (5) for k sufficiently large. This proves the existence of a guided mode for $\varphi < 0$ and for all admissible values of σ .

3 A generalization of V.M. Babich's result

Together with the Rayleigh wave (8) we consider another Rayleigh wave

$$V^R(x_1, x_2, x_3, t) = e^{-i\omega t + ikx_3} u^R(\sin \varphi x_1 - \cos \varphi x_2), \quad (10)$$

which propagates in the direction $(0,0,1)$ and leaves the plane $\sin \varphi x_1 - \cos \varphi x_2 = 0$ free of traction.

As a test function we take a linear combination of the “cut-off” Rayleigh-wave profiles (8) and (10):

$$v_n^{\text{test}}(x_1, x_2) = \alpha \eta(x_1) u^R(x_2) + \beta \eta(\cos \varphi x_1 + \sin \varphi x_2) u^R(\sin \varphi x_1 - \cos \varphi x_2), \quad (11)$$

where for $\varphi < \pi/2$ each term vanishes outside the corresponding right triangle adjacent to the apex (see Fig. 3), while for $\varphi \geq \pi/2$ it vanishes outside the corresponding semi-infinite strip bounded by the wedge face (see Fig. 2).

It is clear that

$$\Phi(v_n^{\text{test}}) = \frac{\mathfrak{A}_n(\alpha, \beta)}{\mathfrak{B}_n(\alpha, \beta)},$$

where \mathfrak{A}_n and \mathfrak{B}_n are quadratic forms on \mathbb{R}^2 . Hence, the inequality $\Phi(v_n^{\text{test}}) < c_R^2 k^2$ for some α, β is equivalent to the presence of a negative eigenvalue of the form $\mathfrak{A}_n - c_R^2 k^2 \mathfrak{B}_n$.

A direct calculation gives

$$\mathfrak{A}_n(\alpha, \beta) - c_R^2 k^2 \mathfrak{B}_n(\alpha, \beta) = \mathfrak{M}(\alpha, \beta) + O\left(\frac{1}{k}\right), \quad k \rightarrow \infty,$$

where \mathfrak{M} is a quadratic form whose matrix M :

$$\begin{bmatrix} \mathfrak{m}_1 & \mathfrak{m}_2 \\ \mathfrak{m}_2 & \mathfrak{m}_1 \end{bmatrix}$$

does not depend on k .

Obviously the form \mathfrak{M} has eigenvectors $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$. It is also easy to see that if the negative eigenvalue corresponds to the eigenvector $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$, then for sufficiently large k the inequality $\Phi(v_n^{\text{test}}) < c_R^2 k^2$ is attained on an antisymmetric function, which yields $\inf_{\mathcal{H}_a} \Phi(u) < c_R^2 k^2$ and thus proves the existence of an antisymmetric mode. Similarly, the presence of a negative eigenvalue with eigenvector $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ proves the existence of a symmetric mode.

Using elementary facts from linear algebra, we obtain the following criteria for the existence of guided modes¹:

I	$ \mathfrak{m}_1 < \mathfrak{m}_2$	antisymmetric mode
II	$ \mathfrak{m}_1 < -\mathfrak{m}_2$	symmetric mode
III	$ \mathfrak{m}_2 < -\mathfrak{m}_1$	both antisymmetric and symmetric modes

The results of the computations are shown in Fig. 4. From Fig. 4 one can see that the fundamental antisymmetric mode (I) can propagate as a localized wave in a wedge with angle φ up to approximately 101° . For the symmetric mode (II) we were able to prove existence only for small positive values of σ , besides the unrealistic (negative) values of σ . The intersection of the regions (III) corresponds to the case where both modes exist, because for this range of angles $\varphi < \pi/2$ the determinant $\det M > 0$ and the trace

¹The boundary between zones I and III (respectively, II and III) belongs to zone I (respectively, II).

$\text{tr } M < 0$. It should be noted that the determinant of the matrix M vanishes for $\lambda = 0$ and $\varphi = \pi/2$ (see [10]); that is, in the right-angle case with $\sigma = 0$, we could not prove the existence of any mode.

Further use of the ansatz

$$\underline{\sigma} = \inf \Phi \left(\sum_{m=1}^l \alpha_m \eta_m u_m^R \right), \quad u_m \in (H^1(\Omega))^3, \quad u_m \neq 0,$$

$$\Phi \left(\sum_m \alpha_m \eta_m u_m^R \right) := \frac{a_\Omega(ik; \sum_{m=1}^l \alpha_m \eta_m u_m^R, \sum_{m=1}^l \alpha_m \eta_m u_m^R)}{\left\| \sum_{m=1}^l \alpha_m \eta_m u_m^R; (L_2(\Omega))^3 \right\|^2},$$

with several “cut-off” Rayleigh-waves profiles (α_m being their amplitudes)

$$U_m^R(x_1, x_2, x_3, t) = e^{-i\omega t + ikx_3} u_m^R(\sin \beta_m x_1 + \cos \beta_m x_2), \quad m = 1, 2, \dots, l,$$

which travel in the direction $(0, 0, 1)$ and leave the planes $\sin \beta_m x_1 + \cos \beta_m x_2 = 0$ traction-free (here β_m are angles measured clockwise from the positive x_1 -axis), did not enlarge the existence regions of the modes. The only slight improvement was a modest extension of the symmetric-mode region (II) when three Rayleigh waves were taken: two waves travelling along the two wedge faces and one wave “propagating” along the plane $\sin((\pi - \varphi)/2) x_1 + \cos((\pi - \varphi)/2) x_2 = 0$.

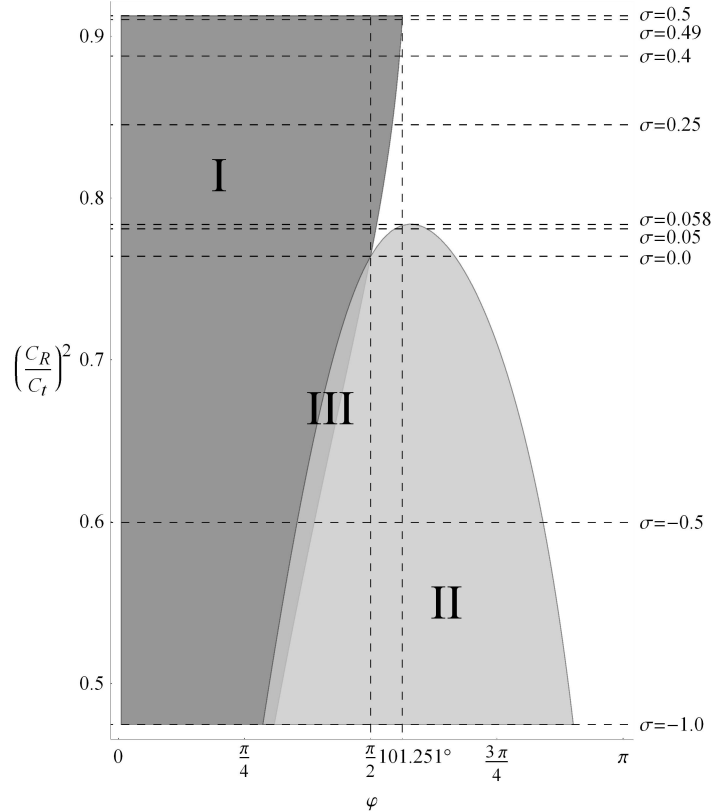


Рис. 4: Existence regions of antisymmetric (I) and symmetric (II) localized guided modes.

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